

# Incremental $\phi$ 60mm Hollow Shaft Type

## Diameter $\phi$ 60mm Hollow shaft type Incremental Rotary encoder

### ■ Features

- External diameter  $\phi$  60mm, inner diameter of shaft  $\phi$  20mm
- Easy installation at narrow space
- Suitable for measuring Angle, Position, Revolution, Speed, Acceleration and distance
- Power supply : 5VDC, 12–24VDC  $\pm$ 5%
- Various output types



**⚠ Please read "Caution for your safety" in operation manual before using.**

### ■ Ordering information

<b>E60H</b>	<b>20</b>	<b>–</b>	<b>8192</b>	<b>–</b>	<b>3</b>	<b>–</b>	<b>N</b>	<b>–</b>	<b>24</b>	<b>–</b>	
Series	Shaft diameter	Pulse/1 Revolution	Output phase	Output	Power supply	Cable					
Diameter $\phi$ 60mm, hollow shaft type	$\phi$ 20mm	5000, 8192	3 : A, B, Z 6 : A, $\bar{A}$ , B, $\bar{B}$ , Z, $\bar{Z}$	T : Totem pole output N : NPN open collector output V : Voltage output L : Line driver output(※)	5 : 5VDC $\pm$ 5% 24 : 12–24VDC $\pm$ 5%	No mark:Normal type (※) C:Cable outgoing connector type					

※Standard : E60H20–[PULSE]–3–N–24

※The power of Line driver is only for 5VDC

※Cable length :250mm

### ■ Specifications

Item		Diameter $\phi$ 60mm hollow shaft type of Incremental rotary encoder		
Resolution(P/R)		5000, 8192		
Electrical specification	Output phase	A, B, Z phase (Line driver output A, $\bar{A}$ , B, $\bar{B}$ , Z, $\bar{Z}$ phase)		
	Phase difference of output	Phase difference between A and B : $\frac{T}{4} \pm \frac{T}{8}$ (T=1cycle of A phase)		
	Control output	Totem pole output	<ul style="list-style-type: none"> <li>• Low <math>\Rightarrow</math> Load current:Max. 30mA, Residual voltage : Max. 0.4VDC</li> <li>• High <math>\Rightarrow</math> Load current:Max. 10mA, Output voltage (Power supply 5VDC):Min. (Power supply–2.0) VDC, Output voltage (Power supply 12–24VDC):Min. (Power supply–3.0) VDC</li> </ul>	
		NPN open collector output	Load current : Max. 30mA, Residual voltage : Max. 0.4VDC	
		Voltage output	Load current : Max. 10mA, Residual voltage : Max. 0.4VDC	
		Line driver output	<ul style="list-style-type: none"> <li>• Low <math>\Rightarrow</math> Load current : Max. 20mA, Residual : Max. 0.5VDC</li> <li>• High <math>\Rightarrow</math> Load current : Max. –20mA, Output voltage : Min. 2.5VDC</li> </ul>	
	Response time (Rise/Fall)	Totem pole output	Max. 1 $\mu$ s	<ul style="list-style-type: none"> <li>• Measuring condition <math>\Rightarrow</math> Cable length : 2m, I sink = Max. 20mA</li> </ul>
		NPN open collector output	Max. 1 $\mu$ s	
		Voltage output	Max. 1 $\mu$ s	
		Line driver output	Max. 0.5 $\mu$ s	
	Max. Response frequency	300kHz		
	Power supply	<ul style="list-style-type: none"> <li>• 5VDC <math>\pm</math>5% (Ripple P–P:Max. 5%)</li> <li>• 12–24VDC <math>\pm</math>5% (Ripple P–P:Max. 5%)</li> </ul>		
	Current consumption	Max. 80mA (disconnection of the load), Line driver output:Max. 50mA (disconnection of the load)		
Insulation resistance	Min. 100M $\Omega$ (at 500VDC mega between all terminals and case)			
Dielectric strength	750VAC 50/60Hz for 1 minute (Between all terminals and case)			
Connection	Cable outgoing type, 200mm cable outgoing connector type			
Mechanical specification	Starting torque	Max. 150gf $\cdot$ cm (0.015N $\cdot$ m)		
	Rotor inertia	Max. 110g $\cdot$ cm <sup>2</sup> (11 $\times$ 10 <sup>–5</sup> kg $\cdot$ m <sup>2</sup> )		
	Shaft loading	Radial : 5kgf, Thrust : 2.5kgf		
	Max. allowable revolution	<b>(Note1)</b>	6000rpm	
Vibration	1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours			
Shock	Max. 100G			
Ambient temperature	–10 ~ 70 $^{\circ}$ C (at non–freezing status), Storage : –25 ~ 85 $^{\circ}$ C			
Ambient humidity	35–85%RH, Storage : 35–90%RH			
Protection	IP50 (IEC standard)			
Cable	$\phi$ 5mm, 5P, Length : 2m, Shield cable (Line driver output : $\phi$ 5mm, 8P)			
Accessory	Bracket			
Unit weight	Approx. 300g			

※ **(Note1)** Not indicated type is customizable.

※ **(Note2)** Max. allowable revolution  $\geq$  Max. response revolution 【Max. response revolution (rpm) =  $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$ 】

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/Speed/Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

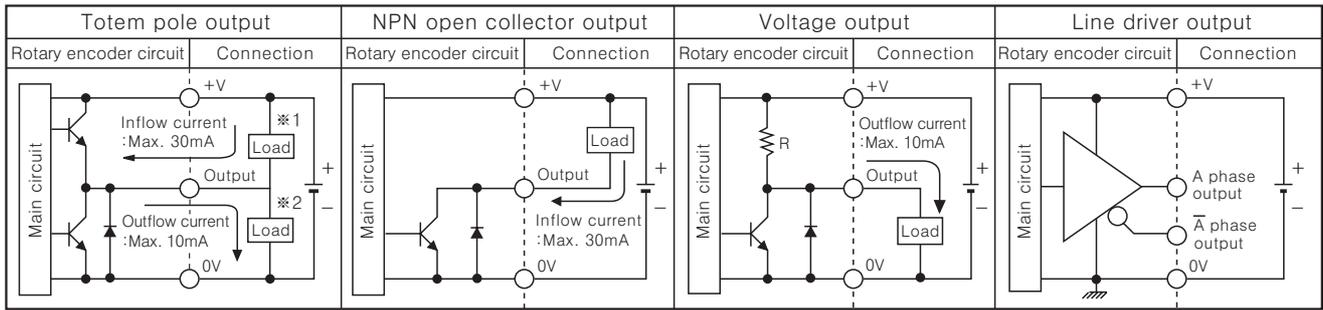
(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Production stoppage models & replacement

# E60H Series

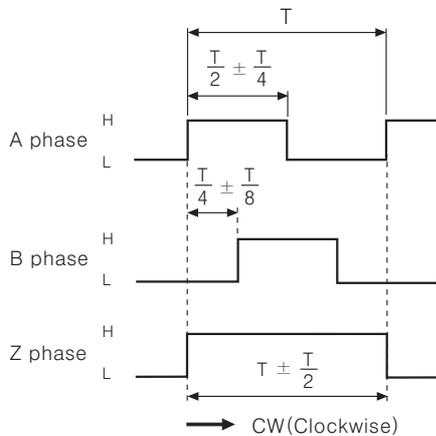
## Control output diagram



- ☞ Totem pole output type can be used for NPN open collector output type(※1) or Voltage output type(※2).
- ☞ All output circuits of A, B, Z phase is same.(Line driver output is A,  $\bar{A}$ , B,  $\bar{B}$ , Z,  $\bar{Z}$ )

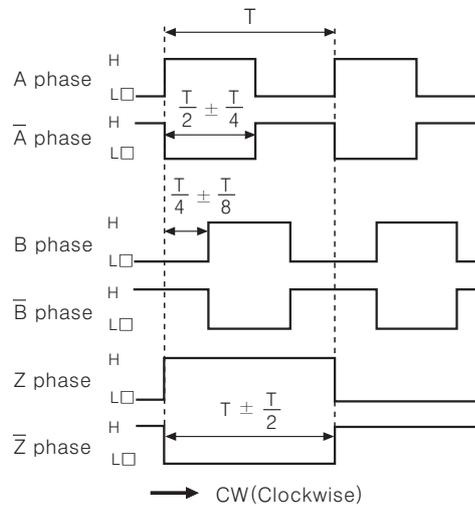
## Output waveform

- Totem pole output / NPN open collector output / Voltage output



※CW : As viewed from the shaft.

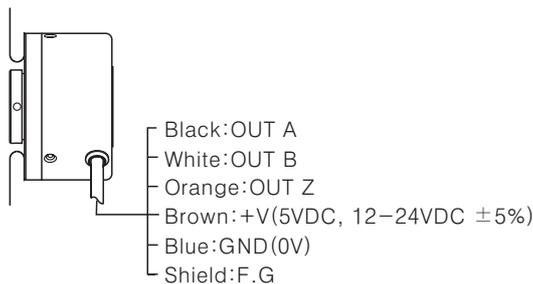
- Line driver output



## Connections

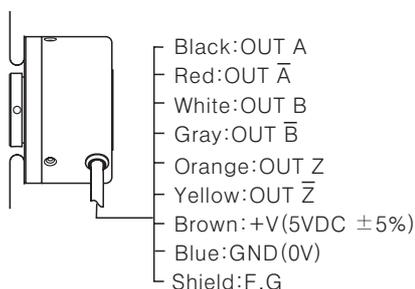
### Normal type

- Totem pole output / NPN open collector output / Voltage output



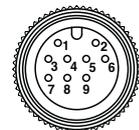
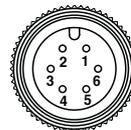
- ※ Unused wires must be insulated.
- ※ The metal case and shield cable of encoder should be grounded(F.G).

- Line driver output



### Cable outgoing connector type

- Totem pole output
- NPN open collector output
- Voltage output
- Line driver output



Totem pole output NPN open collector output Voltage output			Line driver output		
Pin No	Function	Cable color	Pin No	Function	Cable color
①	OUT A	Black	①	OUT A	Black
②	OUT B	White	②	OUT $\bar{A}$	Red
③	OUT Z	Orange	③	+V	Brown
④	+V	Brown	④	GND	Blue
⑤	GND	Blue	⑤	OUT B	White
⑥	F.G	Shield	⑥	OUT $\bar{B}$	Gray
			⑦	OUT Z	Orange
			⑧	OUT $\bar{Z}$	Yellow
			⑨	F.G	Shield

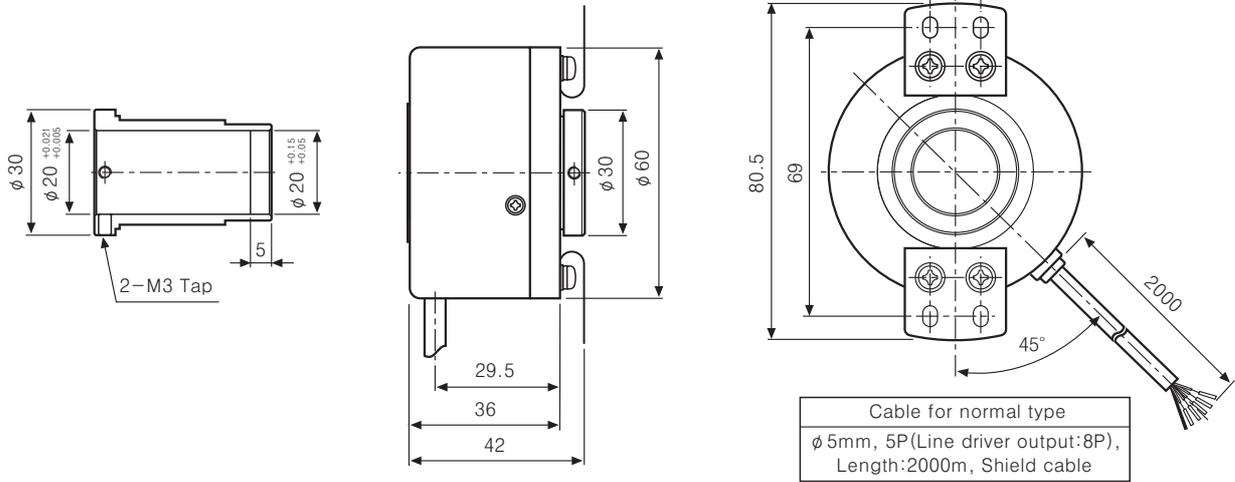
※F.G(Field Ground):It should be grounded separately.

# Incremental $\phi 60\text{mm}$ Hollow Shaft Type

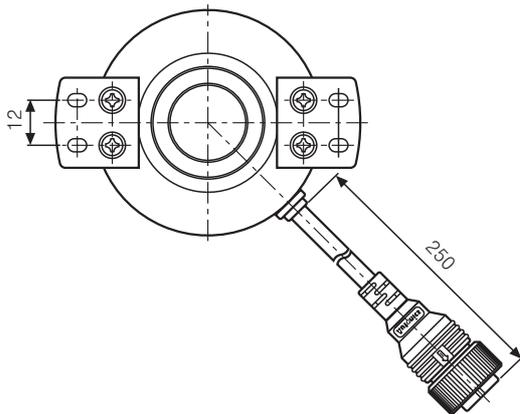
## Dimension

### Normal type

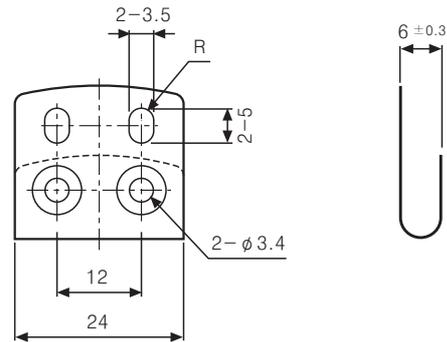
(Unit:mm)



### Cable outgoing connector type



### Bracket



\*Connector cable is customizable and see M-46 for specifications.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/Speed/Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Production stoppage models & replacement